L #	Hits	Search Text	DBs
L1	25295	motion NEAR2 control	USPAT; US-PGPUB
L2	34103	ethernet$8	USPAT; US-PGPUB
L3	909	drive ADJ1 card	USPAT; US-PGPUB
L4	2592	(motor or servo or drive) NEAR10 (intelligen$8 or smart)	USPAT; US-PGPUB
L5	174	4 and 1	USPAT; US-PGPUB
L6	363	4 and 2	USPAT; US-PGPUB
L7	19	4 and 3	USPAT; US-PGPUB
L8	13	4 SAME 2	USPAT; US-PGPUB
L9	196	1 SAME 2	USPAT; US-PGPUB
L10	1	9 and 3	USPAT; US-PGPUB
L11	14	multiaxis NEAR10 application	USPAT; US-PGPUB
L12	2108	Component ADJ2 object ADJ1 model	USPAT; US-PGPUB
L13	0	12 SAME 1	USPAT; US-PGPUB

05/24/2004, EAST Version: 1.4.1

	L #	Hits	Search Text	DBs
14	L14	17	12 and 1	USPAT; US-PGPUB
15	L15	406	12 and 2	USPAT; US-PGPUB
16	L16	23	15 and 6	USPAT; US-PGPUB
17	L17	2	12 and 3	USPAT; US-PGPUB
18	L18	26	12 and 4	USPAT; US-PGPUB
19	L19	0	APInet$4	USPAT; US-PGPUB
20	L20	1405	ethernet SAME (real ADJ1 time)	USPAT; US-PGPUB
21	L21	7	20 and 12	USPAT; US-PGPUB
22	L22	60	20 and 1	USPAT; US-PGPUB
23	L23	1	20 and 3	USPAT; US-PGPUB
24	L24	18	20 and 4	USPAT; US-PGPUB
25	L25	194878	(delay$4 or hold$4) NEAR2 time	USPAT; US-PGPUB
26	L26	374	25 and 4	USPAT; US-PGPUB

	L #	Hits	Search Text	DBs
27	L27	11	25 SAME 4	USPAT; US-PGPUB
28	L28	134	25 SAME 1	USPAT; US-PGPUB
29	L29	208	25 SAME 2	USPAT; US-PGPUB
30	L30	9	25 SAME 3	USPAT; US-PGPUB
31	L31	0	25 SAME 12	USPAT; US-PGPUB
32	L32	20	25 SAME 20	USPAT; US-PGPUB
33	L33	2	kapitan-bri$400.inv.	USPAT; US-PGPUB
34	L34	18	API ADJ2 motion	USPAT; US-PGPUB
35	L39	9123	motion NEAR2 control	EPO; JPO; DERWENT
36	L40	5090	ethernet$8	EPO; JPO; DERWENT
37	L41	206	drive ADJ1 card	EPO; JPO; DERWENT
38	L42	656	(motor or servo or drive) NEAR10 (intelligen$8 or smart)	EPO; JPO; DERWENT
39	L43	0	multiaxis NEAR10 application	EPO; JPO; DERWENT

	L #	Hits	Search Text	DBs
40	L44	73	Component ADJ2 object ADJ1 model	EPO; JPO; DERWENT
41	L45	122	ethernet SAME (real ADJ1 time)	EPO; JPO; DERWENT
42	L46	86040	(delay$4 or hold$4) NEAR2 time	EPO; JPO; DERWENT
43	L47	5	39 and 40	EPO; JPO; DERWENT
44	L48	2	39 and 41	EPO; JPO; DERWENT
45	L49	4	39 and 42	EPO; JPO; DERWENT
46	L50	0	39 and 44	EPO; JPO; DERWENT
47	L51	0	39 and 45	EPO; JPO; DERWENT
48	L52	60	39 and 46	EPO; JPO; DERWENT
49	L53	0	42 and 40	EPO; JPO; DERWENT
50	L54	6	42 and 41	EPO; JPO; DERWENT
51	L55	0	42 and 44	EPO; JPO; DERWENT
52	L56	0	42 and 45	EPO; JPO; DERWENT

	L #	Hits	Search Text	DBs
53	L57	2	42 and 46	EPO; JPO; DERWENT
54	L58	5	45 and 46	EPO; JPO; DERWENT
55	L59	0	45 and 41	EPO; JPO; DERWENT
56	L60	0	45 and 44	EPO; JPO; DERWENT
57	L61	0	40 and 44	EPO; JPO; DERWENT
58	L62	1	40 and 41	EPO; JPO; DERWENT
59	L63	0	kapitan-bri$400.inv.	EPO; JPO; DERWENT; IBM_TDB
60	L64	0	API ADJ2 motion	EPO; JPO; DERWENT; IBM_TDB
61	L65	119	motion NEAR2 control	IBM_TDB
62	L66	118	ethernet$8	IBM_TDB
63	L67	26	drive ADJ1 card	IBM_TDB
64	L68	6	(motor or servo or drive) NEAR10 (intelligen$8 or smart)	IBM_TDB

	L #	Hits	Search Text	DBs
65	L69	0	multiaxis NEAR10 application	IBM_TDB
66	L70	0	Component ADJ2 object ADJ1 model	IBM_TDB
67	L71	4	ethernet SAME (real ADJ1 time)	IBM_TDB
68	L72	1286	(delay$4 or hold$4) NEAR2 time	IBM_TDB
69	L73	0	65 and 66	IBM_TDB
70	L74	3	65 and 72	IBM_TDB
71	L75	3	66 and 72	IBM_TDB

05/24/2004, EAST Version: 1.4.1

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1	INZZ	(motor OR motion) AND (control OR manage)	unrestricted	67443	show titles
2	INZZ	ethernet$	unrestricted	6987	show titles
3	INZZ	(smart OR intelligent) NEAR (drive OR motor OR servo)	unrestricted	533	show titles
4	INZZ	1 AND 2	unrestricted	47	show titles
5	INZZ	1 AND 3	unrestricted	274	show titles
6	INZZ	2 AND 3	unrestricted	5	show titles
7	INZZ	direct-digital-control.DE.	unrestricted	1551	show titles
8	INZZ	7 AND 1	unrestricted	112	show titles
9	INZZ	7 AND 2	unrestricted	5	show titles
10	INZZ	7 AND 3	unrestricted	2	show titles
11	INZZ	PCI	unrestricted	2584	show titles
12	INZZ	11 AND 1	unrestricted	38	show titles
13	INZZ	11 AND 2	unrestricted	75	show titles
14	INZZ	11 AND 3	unrestricted	2	show titles
15	INZZ	timed	unrestricted	4990	show titles
16	INZZ	15 AND 1	unrestricted	60	show titles
17	INZZ	15 AND 2	unrestricted	19	show titles
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